

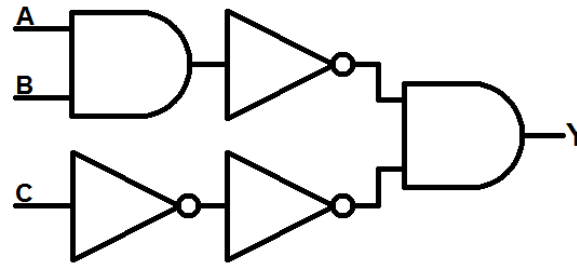
ROBUSTNESS OF SEQUENTIAL CIRCUITS

PRESENTATION BY
SRIKRUPA RAGHURAMAN

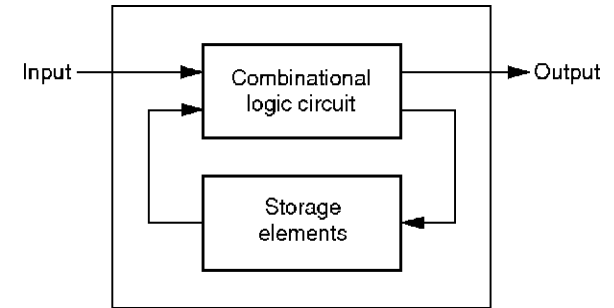
SYNOPSIS



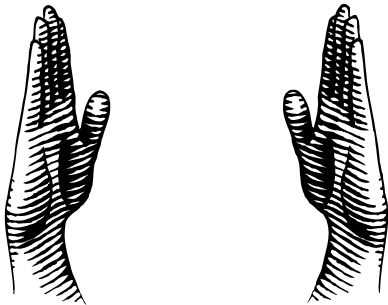
INTRODUCTION



COMBINATORIAL CIRCUITS



SEQUENTIAL CIRCUITS



THE TYPES OF DISTANCES - METRICS

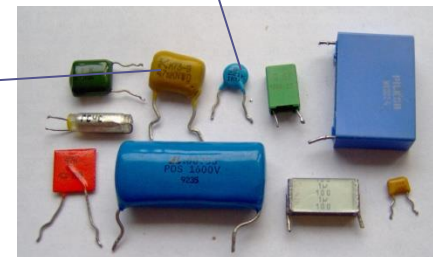
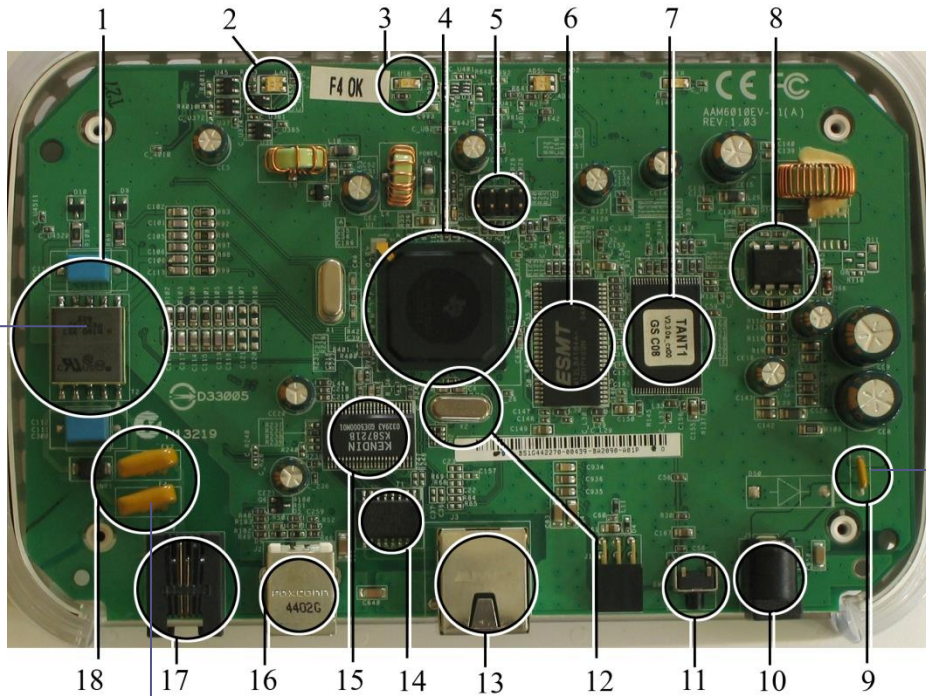


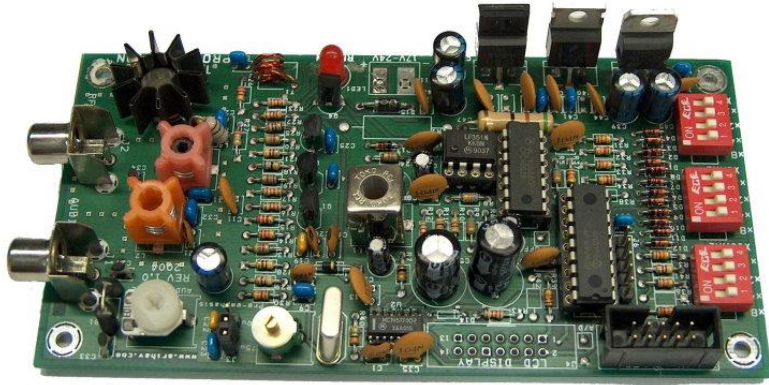
ROBUSTNESS OF SEQUENTIAL CIRCUITS



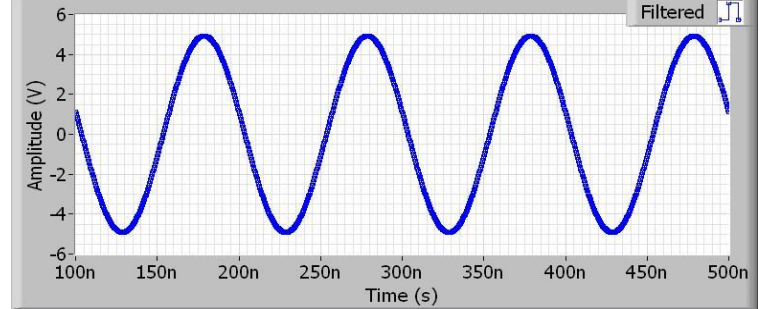
CONCLUSION

EMBEDDED SYSTEMS





DAC Sample and Hold



EMBEDDED SYSTEMS



Software

www.cavsi.com



System



Application

MAIN CHALLENGE

EXTERNAL
PERTURBATIONS

POOR ACCURACY
OF SENSORS

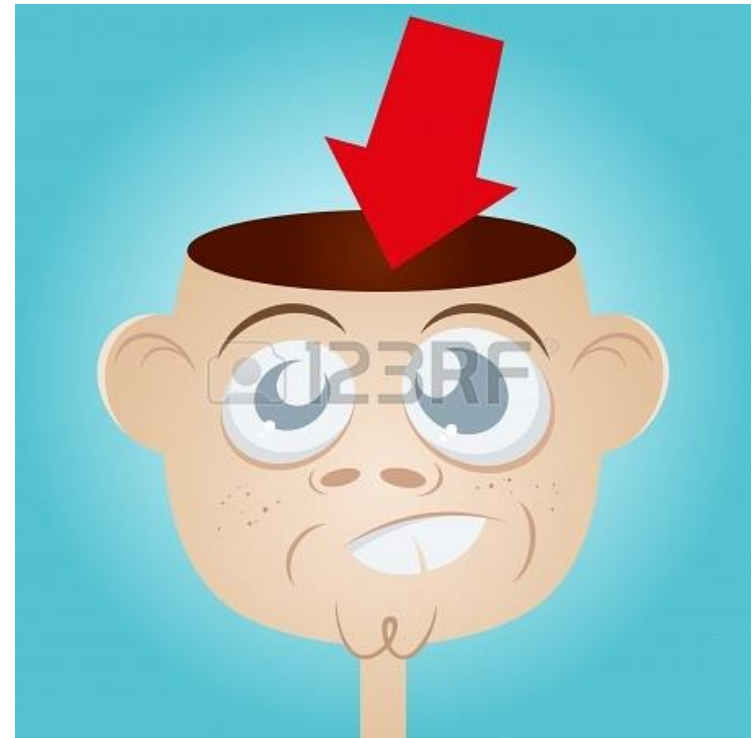
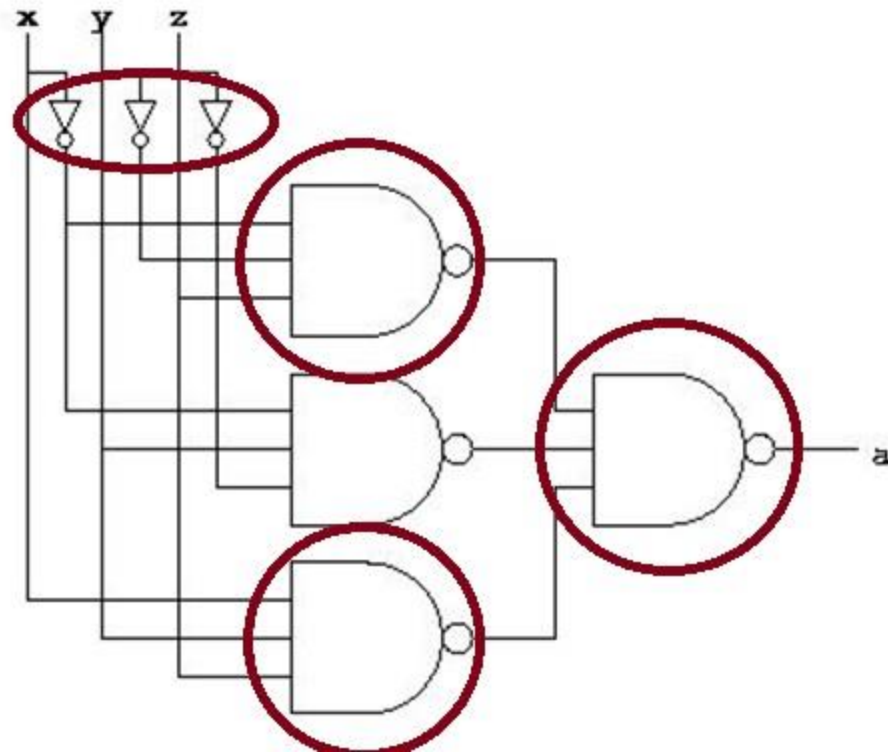
UNCERTAIN INPUTS

UNPREDICTABLE
DELAYS



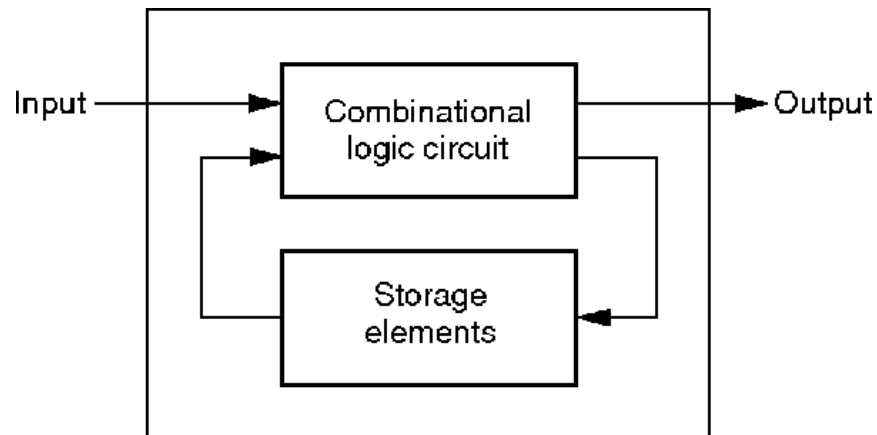
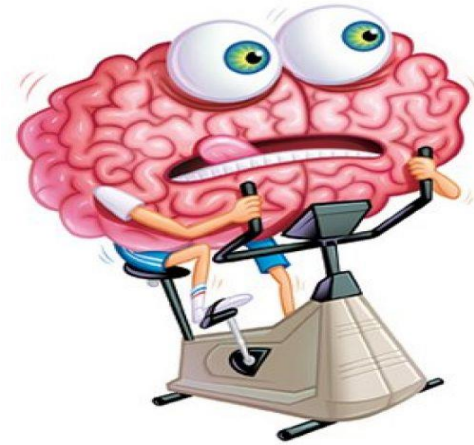
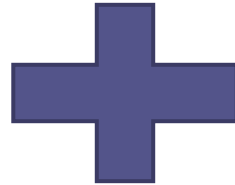
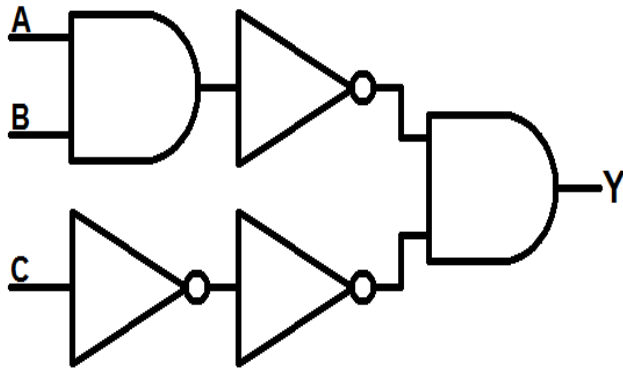
ROBUST BEHAVIOUR

COMBINATORIAL CIRCUITS



OUTPUT AT TIME “T” depends on INPUT AT TIME “T”

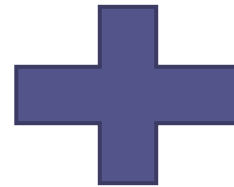
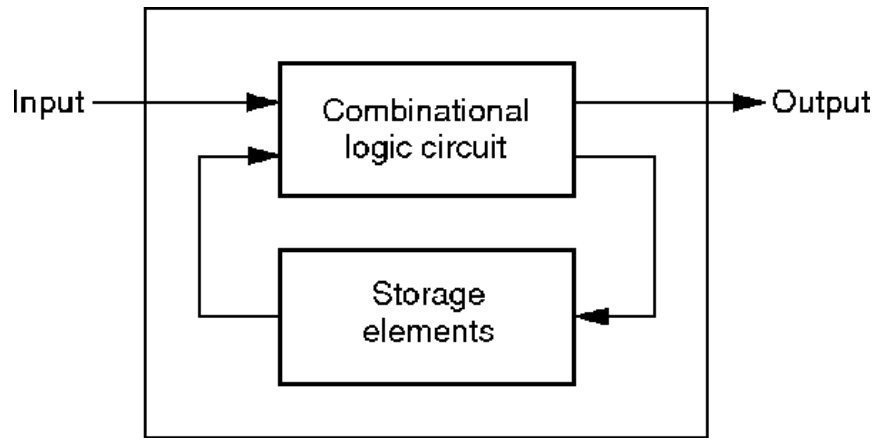
SEQUENTIAL CIRCUITS





- ✓ DELAY = shifts input values by one time step.
- ✓ Output Value at time $t > 0$ = Input Value at time $t - 1$.

CYCLIC CIRCUITS



➤ **CYCLES IN SEQUENTIAL CIRCUITS = FEEDBACK LOOPS**

➤ **OUTPUT AT TIME T = INPUT AT TIME “T” AND T-1 (present and past inputs)**

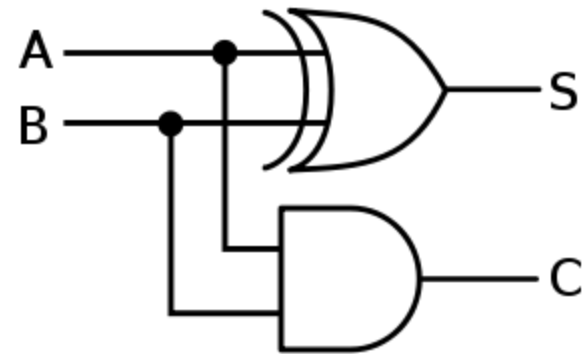
ROBUSTNESS OF SEQUENTIAL CIRCUITS

TO NOTE:

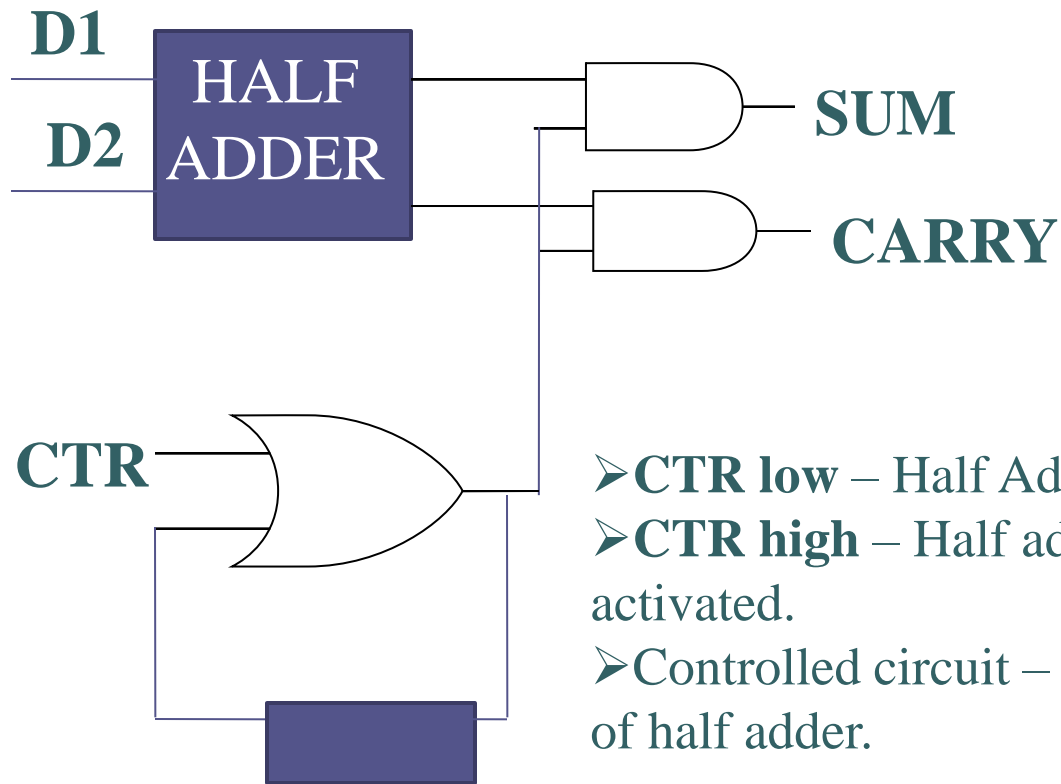
➤ **DISTURBANCE VARIABLES**
– ENVIRONMENT ACTIONS.

➤ **CONTROL VARIABLES** –
CONTROL ACTIONS

➤ **ROBUSTNESS STUDIED**
WITH RESPECT TO
DISTURBANCE VARIABLES.



Output at any time “t”
depends on Inputs A and B
at time “t”



- **CTR low** – Half Adder is inactive.
- **CTR high** – Half adder irreversibly activated.
- Controlled circuit – copies output values of half adder.

HAMMING AND LEVENSHTTEIN DISTANCES

- **STANDARD METRICS** – Measures similarities between pairs of sequences.
- **HAMMING DISTANCE**

Example: **toned**
roses

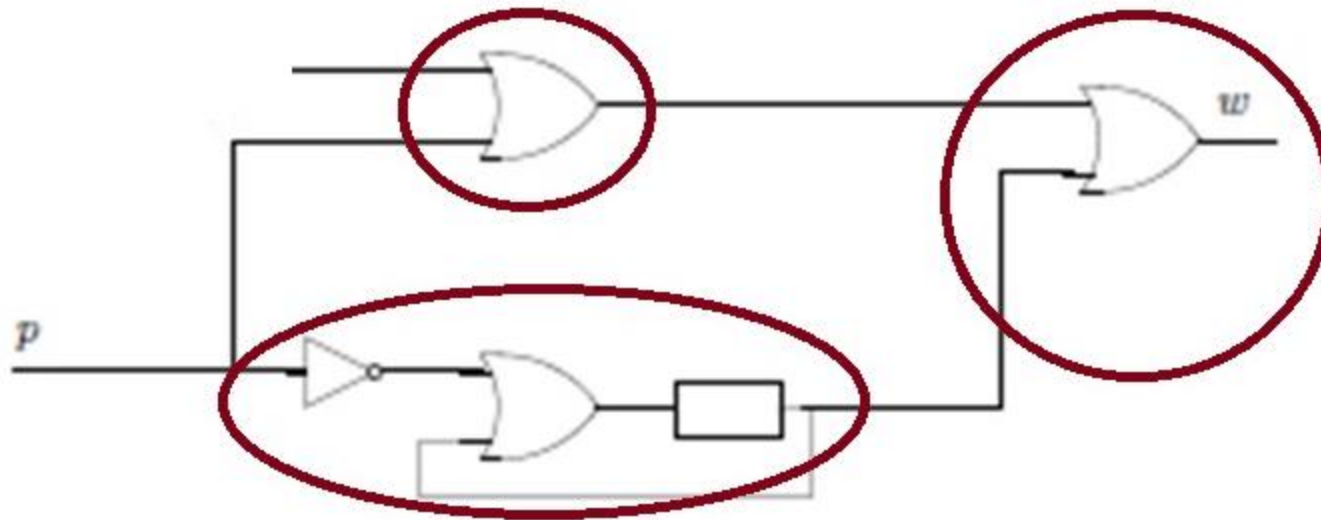
Hamming Distance is 3

1011101
1001001

Hamming Distance is 2

➤ LEVENSHTEIN DISTANCE

➤ Example: **kitten**
sitting } The Levenshtein distance is 3



$$\sigma_1 : \bar{p} \cdot p^{2n} \cdot \bar{p} \cdot p^\omega$$

$$\sigma_2 : p \cdot p^{2n} \cdot \bar{p} \cdot p^\omega$$

$$\gamma_1 : w \cdot w^{2n} \cdot \underline{w} \cdot w^\omega$$

$$\gamma_2 : w \cdot w^{2n} \cdot \underline{\bar{w}} \cdot w^\omega$$

p = single disturbance variable

w = output variable

DRAWBACK:

Error Observed at: (2n+2)th position

COMMON SUFFIX DISTANCE

100000111010011111

100000111010111111

FINITE DISTURBANCE HORIZON

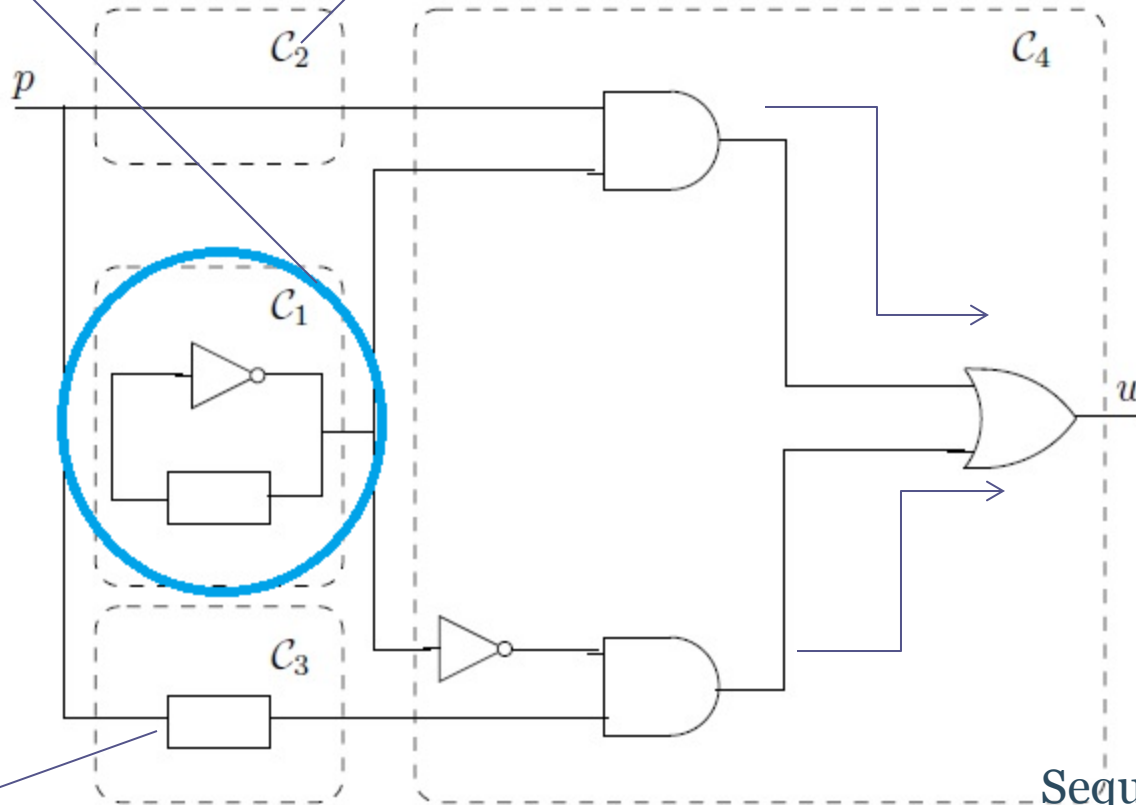
- Bound $-b$, last mismatching position k
- Last mismatching in output sequence occurs before $k+b$

Modulo 2 counter using feedback loop. Has no input.

Dependant on present input

Circuit has finite disturbance memory

$$\Sigma_D = \{p, \bar{p}\}$$



$$w^t = p^t \text{ (t is even)}$$
$$w^t = p^{t-1} \text{ (t is odd)}$$

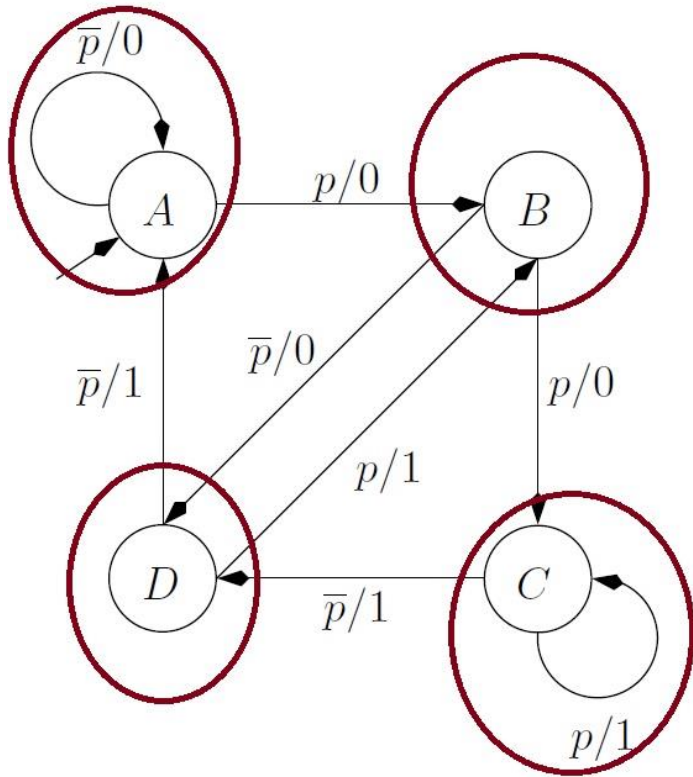
Dependant on previous time step

Sequential Circuit is Σ_D -Robust if and only if it has finite disturbance horizon

MEALY MACHINES

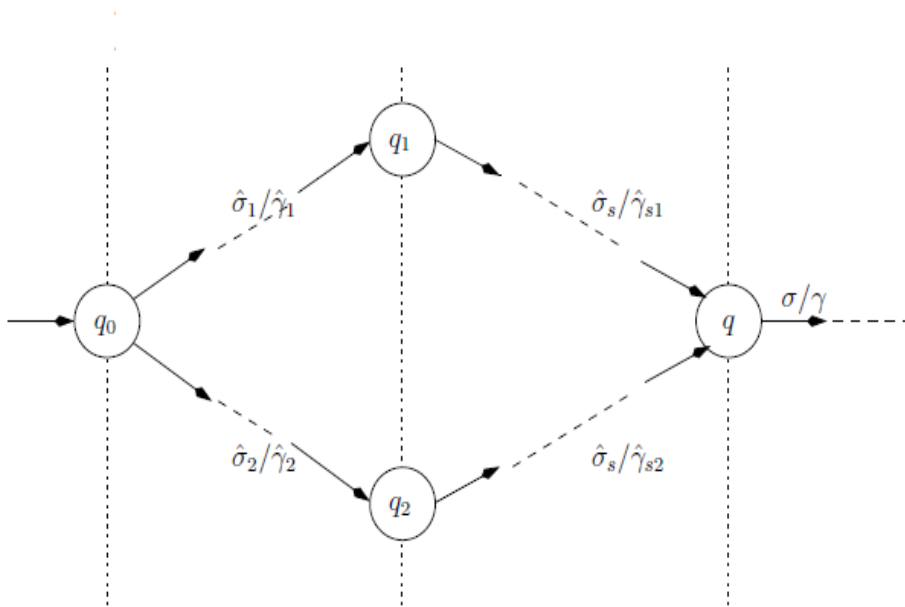
➤ Graphical Representation of Sequential circuits

$$\Sigma_D = \{p, \bar{p}\}$$



**FINITE
STATES**

TO CHECK ROBUSTNESS FOR SEQUENTIAL CIRCUITS



CRITERIA:

ΣD – SYNCHRONIZED

ALGORITHM:

“When there exists a length β on all input words, then from every pair of states a single (output state) is reached”.

TIME COMPLEXITY:

$$O\left(\frac{(|Q|^2 + Q)}{2} \cdot |\Sigma C| \cdot |\Sigma D|^2\right)$$

FUTURE WORK AND CONCLUSION

- Insertion, Suppression of information
- Robustness of Synchronous Circuits
- Two sequential circuits are robust – Which one is better?

LITERATURE

- ❑ Laurent Doyen – LSV, ENS Cachan, France
- ❑ Thomas A. Henzinger – IST Austria, Austria
- ❑ Axel Legay – INRIA – Irisa, France
- ❑ Dejan Nickovic – IST Austria, Austria